Numerical Differentiation & Integration

Gaussian Quadrature

Numerical Analysis (9th Edition) R L Burden & J D Faires

> Beamer Presentation Slides prepared by John Carroll Dublin City University

© 2011 Brooks/Cole, Cengage Learning

(日) (四) (분) (분) (분) 분









## Using Legendre Polynomials to Derive Gaussian Quadrature Formula

→ ∃ → < ∃</p>

4 A N





## Using Legendre Polynomials to Derive Gaussian Quadrature Formula



4 A N





2 Using Legendre Polynomials to Derive Gaussian Quadrature Formula

### 3 Gaussian Quadrature on Arbitrary Intervals

・ 同 ト ・ ヨ ト ・ ヨ

### Features of a Newton-Cotes Formula

Numerical Analysis (Chapter 4)

- T

★ ∃ →

#### Features of a Newton-Cotes Formula

• The Newton-Cotes formulas were derived by integrating interpolating polynomials.

A 3 > A 3

#### Features of a Newton-Cotes Formula

- The Newton-Cotes formulas were derived by integrating interpolating polynomials.
- The error term in the interpolating polynomial of degree *n* involves the (*n* + 1)st derivative of the function being approximated, ...

→ ∃ → < ∃</p>

#### Features of a Newton-Cotes Formula

- The Newton-Cotes formulas were derived by integrating interpolating polynomials.
- The error term in the interpolating polynomial of degree *n* involves the (*n* + 1)st derivative of the function being approximated, ...
- so a Newton-Cotes formula is exact when approximating the integral of any polynomial of degree less than or equal to *n*.

### Features of a Newton-Cotes Formula (Cont'd)

Numerical Analysis (Chapter 4)

Gaussian Quadrature

R L Burden & J D Faires 5 / 40

. . . . . . .

4 A N

#### Features of a Newton-Cotes Formula (Cont'd)

• All the Newton-Cotes formulas use values of the function at equally-spaced points.

• = • •

### Features of a Newton-Cotes Formula (Cont'd)

- All the Newton-Cotes formulas use values of the function at equally-spaced points.
- This restriction is convenient when the formulas are combined to form the composite rules which we considered earlier, ...

( ) < ) < )</p>

### Features of a Newton-Cotes Formula (Cont'd)

- All the Newton-Cotes formulas use values of the function at equally-spaced points.
- This restriction is convenient when the formulas are combined to form the composite rules which we considered earlier, ...
- but it can significantly decrease the accuracy of the approximation.

→ B → < B</p>

4 D b 4 A b

Consider, for example, the Trapezoidal rule applied to determine the integrals of the functions whose graphs are as shown.



It approximates the integral of the function by integrating the linear function that joins the endpoints of the graph of the function.

Numerical Analysis (Chapter 4)

Gaussian Quadrature

R L Burden & J D Faires 6 / 40

# Gaussian Integration: Optimal integration points

But this is not likely the best line for approximating the integral. Lines such as those shown below would likely give much better approximations in most cases.



Gaussian quadrature chooses the points for evaluation in an optimal, rather than equally-spaced, way.

Numerical Analysis (Chapter 4)

Gaussian Quadrature

**Choice of Integration Nodes** 

Numerical Analysis (Chapter 4)

→ B → < B</p>

< 17 ▶

## Choice of Integration Nodes

• The nodes  $x_1, x_2, ..., x_n$  in the interval [a, b] and coefficients  $c_1, c_2, ..., c_n$ , are chosen to minimize the expected error obtained in the approximation

$$\int_a^b f(x) \ dx \approx \sum_{i=1}^n c_i f(x_i).$$

. . . . . . .

### Choice of Integration Nodes

• The nodes  $x_1, x_2, ..., x_n$  in the interval [a, b] and coefficients  $c_1, c_2, ..., c_n$ , are chosen to minimize the expected error obtained in the approximation

$$\int_a^b f(x) \ dx \approx \sum_{i=1}^n c_i f(x_i).$$

 To measure this accuracy, we assume that the best choice of these values produces the exact result for the largest class of polynomials, ...

### Choice of Integration Nodes

• The nodes  $x_1, x_2, ..., x_n$  in the interval [a, b] and coefficients  $c_1, c_2, ..., c_n$ , are chosen to minimize the expected error obtained in the approximation

$$\int_a^b f(x) \ dx \approx \sum_{i=1}^n c_i f(x_i).$$

- To measure this accuracy, we assume that the best choice of these values produces the exact result for the largest class of polynomials, ...
- that is, the choice that gives the greatest degree of precision.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

$$\int_a^b f(\mathbf{x}) \ d\mathbf{x} \approx \sum_{i=1}^n c_i f(\mathbf{x}_i).$$

### Choice of Integration Nodes (Cont'd)

Numerical Analysis (Chapter 4)

4 A 1

$$\int_a^b f(x) \, dx \approx \sum_{i=1}^n c_i f(x_i).$$

### Choice of Integration Nodes (Cont'd)

• The coefficients  $c_1, c_2, ..., c_n$  in the approximation formula are arbitrary, and the nodes  $x_1, x_2, ..., x_n$  are restricted only by the fact that they must lie in [a, b], the interval of integration.

A B > A B

$$\int_a^b f(x) \ dx \approx \sum_{i=1}^n c_i f(x_i).$$

### Choice of Integration Nodes (Cont'd)

- The coefficients  $c_1, c_2, ..., c_n$  in the approximation formula are arbitrary, and the nodes  $x_1, x_2, ..., x_n$  are restricted only by the fact that they must lie in [a, b], the interval of integration.
- This gives us 2*n* parameters to choose.

A B A A B A

4 D b 4 A b

$$\int_a^b f(x) \, dx \approx \sum_{i=1}^n c_i f(x_i).$$

### Choice of Integration Nodes (Cont'd)

Numerical Analysis (Chapter 4)

・ 同 ト ・ ヨ ト ・ ヨ

$$\int_a^b f(x) \ dx \approx \sum_{i=1}^n c_i f(x_i).$$

### Choice of Integration Nodes (Cont'd)

 If the coefficients of a polynomial are considered parameters, the class of polynomials of degree at most 2n – 1 also contains 2n parameters.

▲ 同 ▶ → 三 ▶

$$\int_a^b f(x) \ dx \approx \sum_{i=1}^n c_i f(x_i).$$

### Choice of Integration Nodes (Cont'd)

- If the coefficients of a polynomial are considered parameters, the class of polynomials of degree at most 2n – 1 also contains 2n parameters.
- This, then, is the largest class of polynomials for which it is reasonable to expect a formula to be exact.

→ ∃ →

$$\int_a^b f(x) \, dx \approx \sum_{i=1}^n c_i f(x_i).$$

### Choice of Integration Nodes (Cont'd)

- If the coefficients of a polynomial are considered parameters, the class of polynomials of degree at most 2n – 1 also contains 2n parameters.
- This, then, is the largest class of polynomials for which it is reasonable to expect a formula to be exact.
- With the proper choice of the values and constants, exactness on this set can be obtained.

10/40

#### Example: Formula when n = 2 on [-1, 1]

Suppose we want to determine  $c_1$ ,  $c_2$ ,  $x_1$ , and  $x_2$  so that the integration formula

$$\int_{-1}^{1} f(x) \, dx \approx c_1 f(x_1) + c_2 f(x_2)$$

gives the exact result whenever f(x) is a polynomial of degree 2(2) - 1 = 3 or less, that is, when

$$f(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3,$$

for some collection of constants,  $a_0$ ,  $a_1$ ,  $a_2$ , and  $a_3$ .

### Finding the Formula Coefficients (1/3)

Because

$$\int (a_0 + a_1 x + a_2 x^2 + a_3 x^3) dx$$
  
=  $a_0 \int 1 dx + a_1 \int x dx + a_2 \int x^2 dx + a_3 \int x^3 dx$ 

this is equivalent to showing that the formula gives exact results when f(x) is 1, x,  $x^2$ , and  $x^3$ .

### Finding the Formula Coefficients (2/3)

Hence, we need  $c_1$ ,  $c_2$ ,  $x_1$ , and  $x_2$ , so that

$$c_1 \cdot 1 + c_2 \cdot 1 = \int_{-1}^{1} 1 \, dx = 2$$

### Finding the Formula Coefficients (2/3)

Hence, we need  $c_1$ ,  $c_2$ ,  $x_1$ , and  $x_2$ , so that

$$c_1 \cdot 1 + c_2 \cdot 1 = \int_{-1}^{1} 1 \, dx = 2$$
  
 $c_1 \cdot x_1 + c_2 \cdot x_2 = \int_{-1}^{1} x \, dx = 0$ 

### Finding the Formula Coefficients (2/3)

Hence, we need  $c_1$ ,  $c_2$ ,  $x_1$ , and  $x_2$ , so that

$$c_{1} \cdot 1 + c_{2} \cdot 1 = \int_{-1}^{1} 1 \, dx = 2$$
  

$$c_{1} \cdot x_{1} + c_{2} \cdot x_{2} = \int_{-1}^{1} x \, dx = 0$$
  

$$c_{1} \cdot x_{1}^{2} + c_{2} \cdot x_{2}^{2} = \int_{-1}^{1} x^{2} \, dx = \frac{2}{3}$$

< 🗇 🕨 < 🖻 > <

### Finding the Formula Coefficients (2/3)

Hence, we need  $c_1$ ,  $c_2$ ,  $x_1$ , and  $x_2$ , so that

$$c_{1} \cdot 1 + c_{2} \cdot 1 = \int_{-1}^{1} 1 \, dx = 2$$
  

$$c_{1} \cdot x_{1} + c_{2} \cdot x_{2} = \int_{-1}^{1} x \, dx = 0$$
  

$$c_{1} \cdot x_{1}^{2} + c_{2} \cdot x_{2}^{2} = \int_{-1}^{1} x^{2} \, dx = \frac{2}{3}$$
  

$$c_{1} \cdot x_{1}^{3} + c_{2} \cdot x_{2}^{3} = \int_{-1}^{1} x^{3} \, dx = 0$$

Numerical Analysis (Chapter 4)

< 🗇 > < 🖻 > <

### Finding the Formula Coefficients (3/3)

A little algebra shows that this system of equations has the unique solution

$$c_1 = 1$$
,  $c_2 = 1$ ,  $x_1 = -\frac{\sqrt{3}}{3}$  and  $x_2 = \frac{\sqrt{3}}{3}$ 

э

### Finding the Formula Coefficients (3/3)

A little algebra shows that this system of equations has the unique solution

$$c_1 = 1$$
,  $c_2 = 1$ ,  $x_1 = -\frac{\sqrt{3}}{3}$  and  $x_2 = \frac{\sqrt{3}}{3}$ 

which gives the approximation formula

$$\int_{-1}^{1} f(x) \, dx \approx f\left(\frac{-\sqrt{3}}{3}\right) + f\left(\frac{\sqrt{3}}{3}\right)$$

Numerical Analysis (Chapter 4)

э

### Finding the Formula Coefficients (3/3)

A little algebra shows that this system of equations has the unique solution

$$c_1 = 1$$
,  $c_2 = 1$ ,  $x_1 = -\frac{\sqrt{3}}{3}$  and  $x_2 = \frac{\sqrt{3}}{3}$ 

which gives the approximation formula

$$\int_{-1}^{1} f(x) \, dx \approx f\left(\frac{-\sqrt{3}}{3}\right) + f\left(\frac{\sqrt{3}}{3}\right)$$

This formula has degree of precision 3, that is, it produces the exact result for every polynomial of degree 3 or less.

Numerical Analysis (Chapter 4)

14/40



## Gaussian Quadrature & Optimal Nodes

# Using Legendre Polynomials to Derive Gaussian Quadrature Formula



・ 同 ト ・ ヨ ト ・ ヨ
#### An Alternative Method of Derivation

Numerical Analy	/sis (Cha	pter 4)
-----------------	-----------	---------

< 17 ▶

#### An Alternative Method of Derivation

 We will consider an approach which generates more easily the nodes and coefficients for formulas that give exact results for higher-degree polynomials.

4 A N

#### An Alternative Method of Derivation

- We will consider an approach which generates more easily the nodes and coefficients for formulas that give exact results for higher-degree polynomials.
- This will be achieved using a particular set of orthogonal polynomials (functions with the property that a particular definite integral of the product of any two of them is 0).

< □ > < 同 > < 回 > <

### An Alternative Method of Derivation

- We will consider an approach which generates more easily the nodes and coefficients for formulas that give exact results for higher-degree polynomials.
- This will be achieved using a particular set of orthogonal polynomials (functions with the property that a particular definite integral of the product of any two of them is 0).
- This set is the is the Legendre polynomials, a collection  $\{P_0(x), P_1(x), \dots, P_n(x), \dots, \}$  with properties:
  - (1) For each n,  $P_n(x)$  is a monic polynomial of degree n.

(2)  $\int_{-1}^{1} P(x)P_n(x) dx = 0$  whenever P(x) is a polynomial of degree less than *n*.

16/40

→ 3 → 4 3

< 🗇 🕨

The first few Legendre Polynomials

$$P_0(x) = 1,$$
  $P_1(x) = x,$   $P_2(x) = x^2 - \frac{1}{3}$   
 $P_3(x) = x^3 - \frac{3}{5}x$  and  $P_4(x) = x^4 - \frac{6}{7}x^2 + \frac{3}{35}$ 

Numerical Analysis (Chapter 4)

The first few Legendre Polynomials

$$P_0(x) = 1,$$
  $P_1(x) = x,$   $P_2(x) = x^2 - \frac{1}{3}$   
 $P_3(x) = x^3 - \frac{3}{5}x$  and  $P_4(x) = x^4 - \frac{6}{7}x^2 + \frac{3}{35}$ 

 The roots of these polynomials are distinct, lie in the interval (-1, 1), have a symmetry with respect to the origin, and, most importantly,

The first few Legendre Polynomials

$$P_0(x) = 1,$$
  $P_1(x) = x,$   $P_2(x) = x^2 - \frac{1}{3}$   
 $P_3(x) = x^3 - \frac{3}{5}x$  and  $P_4(x) = x^4 - \frac{6}{7}x^2 + \frac{3}{35}$ 

- The roots of these polynomials are distinct, lie in the interval (-1, 1), have a symmetry with respect to the origin, and, most importantly,
- they are the correct choice for determining the parameters that give us the nodes and coefficients for our quadrature method.

F

The first few Legendre Polynomials

$$P_0(x) = 1,$$
  $P_1(x) = x,$   $P_2(x) = x^2 - \frac{1}{3}$   
 $P_3(x) = x^3 - \frac{3}{5}x$  and  $P_4(x) = x^4 - \frac{6}{7}x^2 + \frac{3}{35}$ 

- The roots of these polynomials are distinct, lie in the interval (-1, 1), have a symmetry with respect to the origin, and, most importantly,
- they are the correct choice for determining the parameters that give us the nodes and coefficients for our quadrature method.

The nodes  $x_1, x_2, ..., x_n$  needed to produce an integral approximation formula that gives exact results for any polynomial of degree less than 2n are the roots of the *n*th-degree Legendre polynomial.

Numerical Analysis (Chapter 4)

Gaussian Quadrature

#### Theorem

Suppose that  $x_1, x_2, ..., x_n$  are the roots of the *n*th Legendre polynomial  $P_n(x)$  and that for each i = 1, 2, ..., n, the numbers  $c_i$  are defined by

$$c_i = \int_{-1}^1 \prod_{\substack{j=1\\j\neq i}}^n \frac{x-x_j}{x_i-x_j} dx$$

#### Theorem

Suppose that  $x_1, x_2, ..., x_n$  are the roots of the *n*th Legendre polynomial  $P_n(x)$  and that for each i = 1, 2, ..., n, the numbers  $c_i$  are defined by

$$c_i = \int_{-1}^1 \prod_{\substack{j=1\\j\neq i}}^n \frac{x-x_j}{x_i-x_j} dx$$

If P(x) is any polynomial of degree less than 2n, then

$$\int_{-1}^{1} P(x) \, dx = \sum_{i=1}^{n} c_i P(x_i)$$

Numerical Analysis (Chapter 4)

### Proof (1/5)

Numerical Analysis (Chapter 4)

・ 同 ト ・ ヨ ト ・ ヨ

### Proof (1/5)

• Let us first consider the situation for a polynomial *P*(*x*) of degree less than *n*.

### Proof (1/5)

- Let us first consider the situation for a polynomial *P*(*x*) of degree less than *n*.
- Re-write P(x) in terms of (n 1)st Lagrange coefficient polynomials with nodes at the roots of the *n*th Legendre polynomial  $P_n(x)$ .

. . . . . . .

### Proof (1/5)

- Let us first consider the situation for a polynomial *P*(*x*) of degree less than *n*.
- Re-write P(x) in terms of (n 1)st Lagrange coefficient polynomials with nodes at the roots of the *n*th Legendre polynomial  $P_n(x)$ .
- The error term for this representation involves the *n*th derivative of P(x).

< ロ > < 同 > < 三 > < 三 >

### Proof (1/5)

- Let us first consider the situation for a polynomial *P*(*x*) of degree less than *n*.
- Re-write P(x) in terms of (n 1)st Lagrange coefficient polynomials with nodes at the roots of the *n*th Legendre polynomial  $P_n(x)$ .
- The error term for this representation involves the *n*th derivative of *P*(*x*).
- Since P(x) is of degree less than n, the nth derivative of P(x) is 0, and this representation of is exact. So

イロン イロン イヨン イヨン

Proof (2/5)

Proof (2/5)

#### Therefore

$$P(x) = \sum_{i=1}^{n} P(x_i) L_i(x) = \sum_{i=1}^{n} \prod_{\substack{j=1 \ i \neq i}}^{n} \frac{x - x_j}{x_i - x_j} P(x_i)$$

Proof (2/5)

Therefore

$$P(x) = \sum_{i=1}^{n} P(x_i) L_i(x) = \sum_{i=1}^{n} \prod_{\substack{j=1 \ j \neq i}}^{n} \frac{x - x_j}{x_i - x_j} P(x_i)$$
$$\int_{-1}^{1} P(x) \, dx = \int_{-1}^{1} \left[ \sum_{\substack{i=1 \ j \neq i}}^{n} \prod_{\substack{j=1 \ j \neq i}}^{n} \frac{x - x_j}{x_i - x_j} P(x_i) \right] \, dx$$

and

Proof (2/5)

Therefore

а

$$P(x) = \sum_{i=1}^{n} P(x_i) L_i(x) = \sum_{i=1}^{n} \prod_{\substack{j=1 \ j\neq i}}^{n} \frac{x - x_j}{x_i - x_j} P(x_i)$$
  
nd 
$$\int_{-1}^{1} P(x) \, dx = \int_{-1}^{1} \left[ \sum_{\substack{i=1 \ j\neq i}}^{n} \prod_{\substack{j=1 \ j\neq i}}^{n} \frac{x - x_j}{x_i - x_j} P(x_i) \right] \, dx$$
$$= \sum_{i=1}^{n} \left[ \int_{-1}^{1} \prod_{\substack{j=1 \ i\neq i}}^{n} \frac{x - x_j}{x_i - x_j} \, dx \right] P(x_i) = \sum_{i=1}^{n} c_i P(x_i)$$

Hence the result is true for polynomials of degree less than n.

Numerical Analysis (Chapter 4)

Gaussian Quadrature

20/40

Proof (3/5)

Numerical Analysis (Chapter 4)

★ E ► ★ E

< 17 ▶

### Proof (3/5)

Now consider a polynomial P(x) of degree at least n but less than 2n.

・ 同 ト ・ ヨ ト ・ ヨ

### Proof (3/5)

- Now consider a polynomial P(x) of degree at least n but less than 2n.
- Divide P(x) by the *n*th Legendre polynomial  $P_n(x)$ .

### Proof (3/5)

- Now consider a polynomial P(x) of degree at least n but less than 2n.
- Divide P(x) by the *n*th Legendre polynomial  $P_n(x)$ .
- This gives two polynomials *Q*(*x*) and *R*(*x*), each of degree less than *n*, with

$$P(x) = Q(x)P_n(x) + R(x)$$

• • • • • • • • • • • •

### Proof (3/5)

- Now consider a polynomial P(x) of degree at least n but less than 2n.
- Divide P(x) by the *n*th Legendre polynomial  $P_n(x)$ .
- This gives two polynomials *Q*(*x*) and *R*(*x*), each of degree less than *n*, with

$$P(x) = Q(x)P_n(x) + R(x)$$

• Note that  $x_i$  is a root of  $P_n(x)$  for each i = 1, 2, ..., n, so we have

$$P(x_i) = Q(x_i)P_n(x_i) + R(x_i) = R(x_i)$$

### Proof (3/5)

- Now consider a polynomial P(x) of degree at least n but less than 2n.
- Divide P(x) by the *n*th Legendre polynomial  $P_n(x)$ .
- This gives two polynomials *Q*(*x*) and *R*(*x*), each of degree less than *n*, with

$$P(x) = Q(x)P_n(x) + R(x)$$

• Note that  $x_i$  is a root of  $P_n(x)$  for each i = 1, 2, ..., n, so we have

$$P(x_i) = Q(x_i)P_n(x_i) + R(x_i) = R(x_i)$$

We now invoke the unique power of the Legendre polynomials.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Proof (4/5)

Numerical Analysis (Chapter 4)

A (10) A (10) A (10)

### Proof (4/5)

First, the degree of the polynomial Q(x) is less than *n*, so (by the Legendre orthogonality property),

$$\int_{-1}^1 \mathsf{Q}(x) \mathsf{P}_n(x) \ dx = 0$$

A (1) > A (1) > A

#### Proof (4/5)

First, the degree of the polynomial Q(x) is less than *n*, so (by the Legendre orthogonality property),

$$\int_{-1}^1 \mathsf{Q}(x) \mathsf{P}_n(x) \ dx = 0$$

Then, since R(x) is a polynomial of degree less than *n*, the opening argument implies that

$$\int_{-1}^{1} R(x) \, dx = \sum_{i=1}^{n} c_i R(x_i)$$

Numerical Analysis (Chapter 4)

< ロ > < 同 > < 三 > < 三

Proof (5/5)

### Proof (5/5)

Putting these facts together verifies that the formula is exact for the polynomial P(x):

### Proof (5/5)

Putting these facts together verifies that the formula is exact for the polynomial P(x):

$$\int_{-1}^{1} P(x) dx = \int_{-1}^{1} [Q(x)P_n(x) + R(x)] dx$$

### Proof (5/5)

Putting these facts together verifies that the formula is exact for the polynomial P(x):

$$\int_{-1}^{1} P(x) dx = \int_{-1}^{1} [Q(x)P_n(x) + R(x)] dx$$
$$= \int_{-1}^{1} R(x) dx$$

### Proof (5/5)

Putting these facts together verifies that the formula is exact for the polynomial P(x):

$$\int_{-1}^{1} P(x) dx = \int_{-1}^{1} [Q(x)P_n(x) + R(x)] dx$$
$$= \int_{-1}^{1} R(x) dx$$
$$= \sum_{i=1}^{n} c_i R(x_i)$$

### Proof (5/5)

Putting these facts together verifies that the formula is exact for the polynomial P(x):

$$\int_{-1}^{1} P(x) dx = \int_{-1}^{1} [Q(x)P_{n}(x) + R(x)] dx$$
  
= 
$$\int_{-1}^{1} R(x) dx$$
  
= 
$$\sum_{i=1}^{n} c_{i}R(x_{i})$$
  
= 
$$\sum_{i=1}^{n} c_{i}P(x_{i})$$

# Gaussian Quadrature: Roots & Coefficients

The constants  $c_i$  needed for the quadrature rule can be generated from the equation given in the theorem:

$$c_i = \int_{-1}^1 \prod_{\substack{j=1\\ i\neq i}}^n \frac{x-x_j}{x_i-x_j} dx$$

but both these constants and the roots of the Legendre polynomials are extensively tabulated.

The following table lists these values for n = 2, 3, 4, and 5.

< ロ > < 同 > < 三 > < 三 >
# Gaussian Quadrature Rules: Roots & Coefficients

n	Roots r <sub>n,i</sub>	Coefficients c <sub>n,i</sub>
2	0.5773502692	1.0000000000
	-0.5773502692	1.0000000000
3	0.7745966692	0.5555555556
	0.0000000000	0.8888888889
	-0.7745966692	0.5555555556
4	0.8611363116	0.3478548451
	0.3399810436	0.6521451549
	-0.3399810436	0.6521451549
	-0.8611363116	0.3478548451
5	0.9061798459	0.2369268850
	0.5384693101	0.4786286705
	0.0000000000	0.5688888889
	-0.5384693101	0.4786286705
	-0.9061798459	0.2369268850

A B > < B</p>

## Gaussian Quadrature: Legendre Polynomials



## Gaussian Quadrature: Legendre Polynomials



# Gaussian Quadrature: Legendre Polynomials



#### Solution

The entries in the table of roots and coefficients . See Table give us

$$\int_{-1}^{1} e^{x} \cos x \, dx \approx 0.\overline{5}e^{0.774596692} \cos 0.774596692 + 0.\overline{8} \cos 0$$
  
+  $0.\overline{5}e^{-0.774596692} \cos(-0.774596692)$   
=  $1.9333904.$ 

Integration by parts can be used to show that the true value of the integral is 1.9334214, so the absolute error is less than  $3.2 \times 10^{-5}$ .

Numerical Analysis (Chapter 4)

Gaussian Quadrature



### Gaussian Quadrature & Optimal Nodes

#### 2 Using Legendre Polynomials to Derive Gaussian Quadrature Formula

#### 3 Gaussian Quadrature on Arbitrary Intervals

Numerical Analysis (Chapter 4)

Gaussian Quadrature

R L Burden & J D Faires 27 / 40

・ 同 ト ・ ヨ ト ・ ヨ

#### Transform the Interval of Integration to [-1, 1]

An integral  $\int_a^b f(x) dx$  over an arbitrary [a, b] can be transformed into an integral over [-1, 1] by using the change of variables  $\bigcirc$  See Diagram:

$$t = \frac{2x - a - b}{b - a} \iff x = \frac{1}{2}[(b - a)t + a + b]$$

< 同 > < 三 > < 三 >

#### Transform the Interval of Integration to [-1, 1]

An integral  $\int_a^b f(x) dx$  over an arbitrary [a, b] can be transformed into an integral over [-1, 1] by using the change of variables  $\bigcirc$  See Diagram:

$$t = \frac{2x - a - b}{b - a} \Longleftrightarrow x = \frac{1}{2}[(b - a)t + a + b]$$

This permits Gaussian quadrature to be applied to any interval [a, b], because

$$\int_{a}^{b} f(x) \, dx = \int_{-1}^{1} f\left(\frac{(b-a)t + (b+a)}{2}\right) \frac{(b-a)}{2} \, dt$$

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

#### Example: Comparing Formulae

Consider the integral

$$\int_{1}^{3} x^{6} - x^{2} \sin(2x) \, dx = 317.3442466.$$

#### Example: Comparing Formulae

Consider the integral

$$\int_{1}^{3} x^{6} - x^{2} \sin(2x) \, dx = 317.3442466.$$

(a) Compare the results for the closed Newton-Cotes formula with n = 1, the open Newton-Cotes formula with n = 1, and Gaussian Quadrature when n = 2.

#### Example: Comparing Formulae

Consider the integral

$$\int_{1}^{3} x^{6} - x^{2} \sin(2x) \, dx = 317.3442466.$$

- (a) Compare the results for the closed Newton-Cotes formula with n = 1, the open Newton-Cotes formula with n = 1, and Gaussian Quadrature when n = 2.
- (b) Compare the results for the closed Newton-Cotes formula with n = 2, the open Newton-Cotes formula with n = 2, and Gaussian Quadrature when n = 3.

29/40

< ロ > < 同 > < 回 > < 回 >

#### Solution: Part (a): Newton-Cotes Formulae (n = 1)

Each of the formulas in this part requires 2 evaluations of the function  $f(x) = x^6 - x^2 \sin(2x)$ . The Newton-Cotes approximations  $\bullet$  See Formulae are:

Closed n = 1 : 
$$\frac{2}{2}[f(1) + f(3)] = 731.6054420$$
  
Open n = 1 :  $\frac{3(2/3)}{2}[f(5/3) + f(7/3)] = 188.7856682$ 

< ロ > < 同 > < 回 > < 回 >

#### Solution: Part (a): Gaussian Quadrature (n = 2)

Gaussian quadrature applied to this problem requires that the integral first be transformed into a problem whose interval of integration is [-1, 1]. Using the  $\bullet$  transformation gives

$$\int_{1}^{3} x^{6} - x^{2} \sin(2x) \, dx = \int_{-1}^{1} (t+2)^{6} - (t+2)^{2} \sin(2(t+2)) \, dt.$$

イロン 不得 とくほう くほう

Solution: Part (a): Gaussian Quadrature (n = 2)

Gaussian quadrature applied to this problem requires that the integral first be transformed into a problem whose interval of integration is [-1, 1]. Using the  $\bigcirc$  transformation gives

$$\int_{1}^{3} x^{6} - x^{2} \sin(2x) \, dx = \int_{-1}^{1} (t+2)^{6} - (t+2)^{2} \sin(2(t+2)) \, dt.$$

Gaussian quadrature with n = 2 then gives

$$\int_{1}^{3} x^{6} - x^{2} \sin(2x) dx$$
  

$$\approx f(-0.5773502692 + 2) + f(0.5773502692 + 2)$$
  

$$= 306.8199344$$

Numerical Analysis (Chapter 4)

イロン 不得 とくほう くほう

#### Solution: Part (b): Newton-Cotes Formulae (n = 2)

Each of the formulas in this part requires 3 function evaluations. The Newton-Cotes approximations See Formulae are:

Closed n = 2:  

$$\frac{1}{3}[f(1) + 4f(2) + f(3)] = 333.2380940$$
Open n = 2:  

$$\frac{4(1/2)}{3}[2f(1.5) - f(2) + 2f(2.5)] = 303.5912023$$

< ロ > < 同 > < 回 > < 国 > < 国 > < 国

#### Solution: Part (b): Gaussian Quadrature (n = 3)

Gaussian quadrature with n = 3, once the  $\bigcirc$  transformation has been done, gives

$$\int_1^3 x^6 - x^2 \sin(2x) \, dx$$

 $\approx 0.\overline{5}f(-0.7745966692+2) + 0.\overline{8}f(2) + 0.\overline{5}f(-0.7745966692+2)$ 

= 317.2641516

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

$$\int_{1}^{3} x^{6} - x^{2} \sin(2x) \, dx = 317.3442466.$$

•

A (10) > A (10) > A

$$\int_{1}^{3} x^{6} - x^{2} \sin(2x) \, dx = 317.3442466.$$

#### Comparison of Results

Newtor	n-Cotes	
Closed	Open	Gaussian Quadrature

|--|

3-Point Rule	333.2380940	303.5912023	317.2641516

The Gaussian quadrature results are clearly superior in each instance.

Numerical Analysis (Chapter 4)

Gaussian Quadrature

R L Burden & J D Faires

・ロト ・ 一 ト ・ ヨ ト ・ ヨ ト

34 / 40

# **Questions?**

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで

# **Reference Material**

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで

# Gaussian Quadrature Rules: Roots & Coefficients

n	Roots r <sub>n,i</sub>	Coefficients c <sub>n,i</sub>
2	0.5773502692	1.0000000000
	-0.5773502692	1.0000000000
3	0.7745966692	0.5555555556
	0.0000000000	0.888888889
	-0.7745966692	0.5555555556
4	0.8611363116	0.3478548451
	0.3399810436	0.6521451549
	-0.3399810436	0.6521451549
	-0.8611363116	0.3478548451
5	0.9061798459	0.2369268850
	0.5384693101	0.4786286705
	0.0000000000	0.5688888889
	-0.5384693101	0.4786286705
	-0.9061798459	0.2369268850

# Mapping Interval [a, b] onto [-1, 1]



Return to Gaussian Quadrature on Arbitrary Intervals (Introduction)

▲ロト ▲団ト ▲ヨト ▲ヨト 三目 - のへで

Return to Gaussian Quadrature on Arbitrary Intervals (Example Part (a))

Return to Gaussian Quadrature on Arbitrary Intervals (Example Part (b))

# Open & Closed Newton-Cotes Formulae (n = 1)

• **Closed** *n* = 1: Trapezoidal Rule:

$$\int_{x_0}^{x_1} f(x) \, dx = \frac{h}{2} [f(x_0) + f(x_1)] - \frac{h^3}{12} f''(\xi)$$

where  $x_0 < \xi < x_1$ .

• Open *n* = 1:

$$\int_{x_{-1}}^{x_2} f(x) \, dx = \frac{3h}{2} [f(x_0) + f(x_1)] + \frac{3h^3}{4} f''(\xi)$$

where  $x_{-1} < \xi < x_2$ .

Return to arbitrary intervals Example (where n = 1

▲ロト ▲団ト ▲ヨト ▲ヨト 三目 - のへで

# Open & Closed Newton-Cotes Formulae (n = 2)

• *n* = 0: Midpoint Rule:

$$\int_{x_{-1}}^{x_1} f(x) \, dx = 2hf(x_0) + \frac{h^3}{3}f''(\xi)$$

where 
$$x_{-1} < \xi < x_1$$
  
• Open  $n = 2$ 

$$\int_{x_{-1}}^{x_3} f(x) \, dx = \frac{4h}{3} [2f(x_0) - f(x_1) + 2f(x_2)] + \frac{14h^5}{45} f^{(4)}(\xi)$$

where  $x_{-1} < \xi < x_3$ .

Return to arbitrary intervals Example (where n = 1

< ロ > (四 > (四 > ( 四 > ( 四 > ) ) ) ( 四 > ( 四 > ) ) ( 四 > ) ( ص > ) (