

# Initial-Value Problems for ODEs

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## Higher-Order Taylor Methods

Numerical Analysis (9th Edition)

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Beamer Presentation Slides

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# Outline

## 1 The Local Truncation Error of a Method

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# Local Truncation Error

## Informal Definition of LTE

The local truncation error at a specified step measures the amount by which the exact solution to the differential equation fails to satisfy the difference equation being used for the approximation at that step.

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- We really want to know how well the approximations generated by the methods satisfy the differential equation, not the other way around.



# Local Truncation Error

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The local truncation error at a specified step measures the amount by which the exact solution to the differential equation fails to satisfy the difference equation being used for the approximation at that step.

## Note

- We really want to know how well the approximations generated by the methods satisfy the differential equation, not the other way around.
- However, we don't know the exact solution so we cannot generally determine this, and the local truncation will serve quite well to determine not only the local error of a method but the actual approximation error.

# Local Truncation Error

IVP

$$y' = f(t, y), \quad a \leq t \leq b, \quad y(a) = \alpha$$

## Definition of LTE

The difference method

$$w_0 = \alpha$$

$$w_{i+1} = w_i + h\phi(t_i, w_i), \quad \text{for each } i = 0, 1, \dots, N-1,$$

# Local Truncation Error

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The difference method

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$$w_{i+1} = w_i + h\phi(t_i, w_i), \quad \text{for each } i = 0, 1, \dots, N-1,$$

has **local truncation error**

$$\tau_{i+1}(h) = \frac{y_{i+1} - (y_i + h\phi(t_i, y_i))}{h} = \frac{y_{i+1} - y_i}{h} - \phi(t_i, y_i),$$

for each  $i = 0, 1, \dots, N-1$ , where  $y_i$  and  $y_{i+1}$  denote the solution at  $t_i$  and  $t_{i+1}$ , respectively.

# Local Truncation Error

## Example: LTE in Euler's Method

Euler's method has local truncation error at the  $i$ th step

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# Local Truncation Error

## Example: LTE in Euler's Method

Euler's method has local truncation error at the  $i$ th step

$$\tau_{i+1}(h) = \frac{y_{i+1} - y_i}{h} - f(t_i, y_i), \quad \text{for each } i = 0, 1, \dots, N - 1$$

- This error is a **local error** because it measures the accuracy of the method at a specific step, assuming that the method was exact at the previous step.
- As such, it depends on the differential equation, the step size, and the particular step in the approximation.

# Local Truncation Error

## LTE in Euler's Method (Cont'd)

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Earlier, we have seen that, for Euler's method:

$$y(t_{i+1}) = y(t_i) + hf(t_i, y(t_i)) + \frac{h^2}{2}y''(\xi_i)$$



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$$\tau_{i+1}(h) = \frac{h}{2}y''(\xi_i), \quad \text{for some } \xi_i \text{ in } (t_i, t_{i+1})$$

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When  $y''(t)$  is known to be bounded by a constant  $M$  on  $[a, b]$ , this implies

$$|\tau_{i+1}(h)| \leq \frac{h}{2}M$$

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When  $y''(t)$  is known to be bounded by a constant  $M$  on  $[a, b]$ , this implies

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so the local truncation error in Euler's method is  $O(h)$ .

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- 2 Higher-Order Taylor Methods**
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# Using Taylor's Theorem

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- Euler's method was derived by using **Taylor's Theorem** with  $n = 1$  to approximate the solution of the differential equation.



# Using Taylor's Theorem

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- One way to select difference-equation methods for solving ordinary differential equations is in such a manner that their local truncation errors are  $O(h^p)$  for as large a value of  $p$  as possible, ...
- while keeping the number and complexity of calculations of the methods within a reasonable bound.
- Euler's method was derived by using **Taylor's Theorem** with  $n = 1$  to approximate the solution of the differential equation.
- Can we extend this technique of derivation to larger values of  $n$  in order to find methods for improving the convergence properties of difference methods?

# Higher-Order Taylor Methods

## Assumption

The solution  $y(t)$  to the initial-value problem

$$y' = f(t, y), \quad a \leq t \leq b, \quad y(a) = \alpha,$$

has  $(n + 1)$  continuous derivatives.

# Higher-Order Taylor Methods

## Assumption

The solution  $y(t)$  to the initial-value problem

$$y' = f(t, y), \quad a \leq t \leq b, \quad y(a) = \alpha,$$

has  $(n + 1)$  continuous derivatives.

## Taylor Expansion about $t_i$

If we expand the solution,  $y(t)$ , in terms of its  $n$ th Taylor polynomial about  $t_i$  and evaluate at  $t_{i+1}$ , we obtain

$$y(t_{i+1}) = y(t_i) + hy'(t_i) + \frac{h^2}{2}y''(t_i) + \cdots + \frac{h^n}{n!}y^{(n)}(t_i) + \frac{h^{n+1}}{(n+1)!}y^{(n+1)}(\xi_i)$$

for some  $\xi_i$  in  $(t_i, t_{i+1})$ .

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Successive differentiation of the solution,  $y(t)$ , gives

$$y'(t) = f(t, y(t)), \quad y''(t) = f'(t, y(t)), \quad \dots \quad y^{(k)}(t) = f^{(k-1)}(t, y(t))$$

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Substituting these results into

$$y(t_{i+1}) = y(t_i) + hy'(t_i) + \frac{h^2}{2}y''(t_i) + \dots + \frac{h^n}{n!}y^{(n)}(t_i) + \frac{h^{n+1}}{(n+1)!}y^{(n+1)}(\xi_i)$$

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gives

$$\begin{aligned} y(t_{i+1}) &= y(t_i) + hf(t_i, y(t_i)) + \frac{h^2}{2}f'(t_i, y(t_i)) + \dots \\ &\quad + \frac{h^n}{n!}f^{(n-1)}(t_i, y(t_i)) + \frac{h^{n+1}}{(n+1)!}f^{(n)}(\xi_i, y(\xi_i)) \end{aligned}$$

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## Derivation (Cont'd)



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The difference-equation method corresponding to

$$\begin{aligned}y(t_{i+1}) &= y(t_i) + hf(t_i, y(t_i)) + \frac{h^2}{2}f'(t_i, y(t_i)) + \cdots \\ &\quad + \frac{h^n}{n!}f^{(n-1)}(t_i, y(t_i)) + \frac{h^{n+1}}{(n+1)!}f^{(n)}(\xi_i, y(\xi_i))\end{aligned}$$

is obtained by deleting the remainder term involving  $\xi_i$ .

# Higher-Order Taylor Methods

## Taylor's Method of order $n$

$$w_0 = \alpha$$

$$w_{i+1} = w_i + hT^{(n)}(t_i, w_i), \quad \text{for each } i = 0, 1, \dots, N-1$$

where

$$T^{(n)}(t_i, w_i) = f(t_i, w_i) + \frac{h}{2}f'(t_i, w_i) + \dots + \frac{h^{n-1}}{n!}f^{(n-1)}(t_i, w_i)$$

Note: Euler's method is Taylor's method of order one.

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# Higher-Order Taylor Methods

## Example: Orders 2 & 4 Methods

Apply Taylor's method of orders

- 2 and
- 4

with  $N = 10$  to the initial-value problem

$$y' = y - t^2 + 1, \quad 0 \leq t \leq 2, \quad y(0) = 0.5$$

# Higher-Order Taylor Methods

## Order 2 Method (1/4)

For the method of order 2 [▶ Taylor's Method](#) we need the first derivative of  $f(t, y(t)) = y(t) - t^2 + 1$  with respect to the variable  $t$ .

# Higher-Order Taylor Methods

## Order 2 Method (1/4)

For the method of order 2 ▶ Taylor's Method we need the first derivative of  $f(t, y(t)) = y(t) - t^2 + 1$  with respect to the variable  $t$ . Because  $y' = y - t^2 + 1$  we have

$$f'(t, y(t)) = \frac{d}{dt}(y - t^2 + 1) = y' - 2t = y - t^2 + 1 - 2t$$

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so

$$T^{(2)}(t_j, w_j) = f(t_j, w_j) + \frac{h}{2}f'(t_j, w_j)$$

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so

$$\begin{aligned} T^{(2)}(t_i, w_i) &= f(t_i, w_i) + \frac{h}{2} f'(t_i, w_i) \\ &= w_i - t_i^2 + 1 + \frac{h}{2}(w_i - t_i^2 + 1 - 2t_i) \end{aligned}$$



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so

$$\begin{aligned} T^{(2)}(t_i, w_i) &= f(t_i, w_i) + \frac{h}{2} f'(t_i, w_i) \\ &= w_i - t_i^2 + 1 + \frac{h}{2}(w_i - t_i^2 + 1 - 2t_i) \\ &= \left(1 + \frac{h}{2}\right)(w_i - t_i^2 + 1) - ht_i \end{aligned}$$

# Higher-Order Taylor Methods

## Order 2 Method (2/4)

Because  $N = 10$  we have  $h = 0.2$ , and  $t_i = 0.2i$  for each  $i = 1, 2, \dots, 10$ .

# Higher-Order Taylor Methods

## Order 2 Method (2/4)

Because  $N = 10$  we have  $h = 0.2$ , and  $t_i = 0.2i$  for each  $i = 1, 2, \dots, 10$ . Thus, the second-order method becomes

$$w_0 = 0.5$$

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$$w_{i+1} = w_i + h \left[ \left( 1 + \frac{h}{2} \right) (w_i - t_i^2 + 1) - ht_i \right]$$

# Higher-Order Taylor Methods

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Because  $N = 10$  we have  $h = 0.2$ , and  $t_i = 0.2i$  for each  $i = 1, 2, \dots, 10$ . Thus, the second-order method becomes

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## Order 2 Method (2/4)

Because  $N = 10$  we have  $h = 0.2$ , and  $t_i = 0.2i$  for each  $i = 1, 2, \dots, 10$ . Thus, the second-order method becomes

$$\begin{aligned}w_0 &= 0.5 \\w_{i+1} &= w_i + h \left[ \left( 1 + \frac{h}{2} \right) (w_i - t_i^2 + 1) - ht_i \right] \\&= w_i + 0.2 \left[ \left( 1 + \frac{0.2}{2} \right) (w_i - 0.04i^2 + 1) - 0.04i \right] \\&= 1.22w_i - 0.0088i^2 - 0.008i + 0.22\end{aligned}$$

# Higher-Order Taylor Methods

## Order 2 Method (3/4)

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The first two steps give the approximations

$$\begin{aligned}y(0.2) \approx w_1 &= 1.22(0.5) - 0.0088(0)^2 - 0.008(0) + 0.22 \\ &= 0.83\end{aligned}$$



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All the approximations and their errors are shown in the following table.

# Higher-Order Taylor Methods

## Order 2 Method (4/4): Summary of Numerical Results

$t_i$	Taylor Order 2 $w_i$	Error $ y(t_i) - w_i $
0.0	0.500000	0
0.2	0.830000	0.000701
0.4	1.215800	0.001712
0.6	1.652076	0.003135
0.8	2.132333	0.005103
$\vdots$	$\vdots$	$\vdots$
1.6	4.306146	0.022663
1.8	4.846299	0.031122
2.0	5.347684	0.042212

# Higher-Order Taylor Methods

## Order 4 Method (1/7)

For the method of order 4 ▶ Taylor's Method we need the first **3** derivatives of  $f(t, y(t))$  with respect to  $t$ .

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$$f'(t, y(t)) = y - t^2 + 1 - 2t$$

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$$\text{and } f'''(t, y(t)) = \frac{d}{dt}(y - t^2 - 2t - 1)$$

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$$\begin{aligned} \text{and } f'''(t, y(t)) &= \frac{d}{dt}(y - t^2 - 2t - 1) = y' - 2t - 2 \\ &= y - t^2 - 2t - 1 \end{aligned}$$

# Higher-Order Taylor Methods

## Order 4 Method (2/7)

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Therefore,

$$T^{(4)}(t_i, w_i) = f(t_i, w_i) + \frac{h}{2}f'(t_i, w_i) + \frac{h^2}{6}f''(t_i, w_i) + \frac{h^3}{24}f'''(t_i, w_i)$$

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## Order 4 Method (2/7)

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# Higher-Order Taylor Methods

## Order 4 Method (2/7)

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 &= w_i - t_i^2 + 1 + \frac{h}{2}(w_i - t_i^2 + 1 - 2t_i) \\
 &\quad + \frac{h^2}{6}(w_i - t_i^2 - 2t_i - 1) + \frac{h^3}{24}(w_i - t_i^2 - 2t_i - 1) \\
 &= \left(1 + \frac{h}{2} + \frac{h^2}{6} + \frac{h^3}{24}\right)(w_i - t_i^2) - \left(1 + \frac{h}{3} + \frac{h^2}{12}\right)(ht_i) \\
 &\quad + 1 + \frac{h}{2} - \frac{h^2}{6} - \frac{h^3}{24}
 \end{aligned}$$



# Higher-Order Taylor Methods

## Order 4 Method (3/7)

# Higher-Order Taylor Methods

## Order 4 Method (3/7)

Hence Taylor's method of order four is

$$\begin{aligned}w_0 &= 0.5, \\w_{i+1} &= w_i + h \left[ \left( 1 + \frac{h}{2} + \frac{h^2}{6} + \frac{h^3}{24} \right) (w_i - t_i^2) - \left( 1 + \frac{h}{3} + \frac{h^2}{12} \right) ht_i \right. \\&\quad \left. + 1 + \frac{h}{2} - \frac{h^2}{6} - \frac{h^3}{24} \right]\end{aligned}$$

for  $i = 0, 1, \dots, N - 1$ .

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Because  $N = 10$  and  $h = 0.2$ , the method becomes

$$w_{i+1} = w_i + 0.2 \left[ \left( 1 + \frac{0.2}{2} + \frac{0.04}{6} + \frac{0.008}{24} \right) (w_i - 0.04i^2) - \left( 1 + \frac{0.2}{3} + \frac{0.04}{12} \right) (0.04i) + 1 + \frac{0.2}{2} - \frac{0.04}{6} - \frac{0.008}{24} \right]$$

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for each  $i = 0, 1, \dots, 9$ .

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All the approximations and their errors are shown in the following table.

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## Order 4 Method (6/7): Summary of Numerical Results

$t_i$	Taylor Order 4 $w_i$	Error $ y(t_i) - w_i $
0.0	0.500000	0
0.2	0.829300	0.000001
0.4	1.214091	0.000003
0.6	1.648947	0.000006
$\vdots$	$\vdots$	$\vdots$
1.4	3.732432	0.000032
1.6	4.283529	0.000045
1.8	4.815238	0.000062
2.0	5.305555	0.000083

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- A comparison of these results with those of Taylor's method of order 2 shows that the 4th-order results are vastly superior.
- The table of results for Taylor's method of order 4 indicate that the method is quite accurate at the nodes 0.2, 0.4, etc.

# Outline

- 1 The Local Truncation Error of a Method
- 2 Higher-Order Taylor Methods
- 3 Example: Taylor Methods of Order 2 & 4
- 4 Local Truncation Error in Taylor Methods (Theorem)**

# Higher-Order Taylor Methods

## Theorem

If Taylor's method of order  $n$  is used to approximate the solution to

$$y'(t) = f(t, y(t)), \quad a \leq t \leq b, \quad y(a) = \alpha,$$

with step size  $h$  and if  $y \in C^{n+1}[a, b]$ , then the local truncation error is  $O(h^n)$ .

# Higher-Order Taylor Methods

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When deriving Taylor Methods, we obtained the expression

$$y(t_{i+1}) = y(t_i) + hy'(t_i) + \frac{h^2}{2}y''(t_i) + \cdots + \frac{h^n}{n!}y^{(n)}(t_i) + \frac{h^{n+1}}{(n+1)!}y^{(n+1)}(\xi_i)$$

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and this can be rewritten in the form

$$\begin{aligned} & y_{i+1} - y_i - hf(t_i, y_i) - \frac{h^2}{2}f'(t_i, y_i) - \cdots - \frac{h^n}{n!}f^{(n-1)}(t_i, y_i) \\ &= \frac{h^{n+1}}{(n+1)!}f^{(n)}(\xi_i, y(\xi_i)) \end{aligned}$$

for some  $\xi_i$  in  $(t_i, t_{i+1})$ .

# Higher-Order Taylor Methods

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# Higher-Order Taylor Methods

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## Proof (2/2)

So the local truncation error is

$$\tau_{i+1}(h) = \frac{y_{i+1} - y_i}{h} - T^{(n)}(t_i, y_i) = \frac{h^n}{(n+1)!}f^{(n)}(\xi_i, y(\xi_i))$$

for each  $i = 0, 1, \dots, N - 1$ .

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$$\begin{aligned} & y_{i+1} - y_i - hf(t_i, y_i) - \frac{h^2}{2}f'(t_i, y_i) - \dots - \frac{h^n}{n!}f^{(n-1)}(t_i, y_i) \\ &= \frac{h^{n+1}}{(n+1)!}f^{(n)}(\xi_i, y(\xi_i)) \end{aligned}$$

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for each  $i = 0, 1, \dots, N-1$ . Since  $y \in C^{n+1}[a, b]$ , we have  $y^{(n+1)}(t) = f^{(n)}(t, y(t))$  bounded on  $[a, b]$  and  $\tau_i(h) = O(h^n)$ , for each  $i = 1, 2, \dots, N$ .

Questions?

# Reference Material

## Taylor's Method of order $n$

$$w_0 = \alpha$$

$$w_{i+1} = w_i + hT^{(n)}(t_i, w_i), \quad \text{for each } i = 0, 1, \dots, N-1$$

where

$$T^{(n)}(t_i, w_i) = f(t_i, w_i) + \frac{h}{2}f'(t_i, w_i) + \dots + \frac{h^{n-1}}{n!}f^{(n-1)}(t_i, w_i)$$

[Return to Example on Taylor's 2nd Order Method](#)

[Return to Example on Taylor's 4th Order Method](#)