

Iterative Techniques in Matrix Algebra

Jacobi & Gauss-Seidel Iterative Techniques II

Numerical Analysis (9th Edition)

R L Burden & J D Faires

Beamer Presentation Slides

prepared by

John Carroll

Dublin City University

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The Gauss-Seidel Method

Looking at the Jacobi Method

- A possible improvement to the Jacobi Algorithm can be seen by re-considering

$$x_i^{(k)} = \frac{1}{a_{ii}} \left[\sum_{\substack{j=1 \\ j \neq i}}^n (-a_{ij}x_j^{(k-1)}) + b_i \right], \quad \text{for } i = 1, 2, \dots, n$$

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- The components of $\mathbf{x}^{(k-1)}$ are used to compute all the components $x_j^{(k)}$ of $\mathbf{x}^{(k)}$.

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- The components of $\mathbf{x}^{(k-1)}$ are used to compute all the components $x_i^{(k)}$ of $\mathbf{x}^{(k)}$.
- But, for $i > 1$, the components $x_1^{(k)}, \dots, x_{i-1}^{(k)}$ of $\mathbf{x}^{(k)}$ have already been computed and are expected to be better approximations to the actual solutions x_1, \dots, x_{i-1} than are $x_1^{(k-1)}, \dots, x_{i-1}^{(k-1)}$.

The Gauss-Seidel Method

Instead of using

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it seems reasonable, then, to compute $x_i^{(k)}$ using these most recently calculated values.

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The Gauss-Seidel Iterative Technique

$$x_i^{(k)} = \frac{1}{a_{ii}} \left[- \sum_{j=1}^{i-1} (a_{ij} x_j^{(k)}) - \sum_{j=i+1}^n (a_{ij} x_j^{(k-1)}) + b_i \right]$$

for each $i = 1, 2, \dots, n$.

The Gauss-Seidel Method

Example

Use the Gauss-Seidel iterative technique to find approximate solutions to

$$10x_1 - x_2 + 2x_3 = 6$$

$$-x_1 + 11x_2 - x_3 + 3x_4 = 25$$

$$2x_1 - x_2 + 10x_3 - x_4 = -11'$$

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starting with $\mathbf{x} = (0, 0, 0, 0)^t$ and iterating until

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Note: The solution $\mathbf{x} = (1, 2, -1, 1)^t$ was approximated by Jacobi's method in an earlier example.

The Gauss-Seidel Method

Solution (1/3)

For the Gauss-Seidel method we write the system, for each $k = 1, 2, \dots$ as

$$\begin{aligned}
 x_1^{(k)} &= \frac{1}{10}x_2^{(k-1)} - \frac{1}{5}x_3^{(k-1)} + \frac{3}{5} \\
 x_2^{(k)} &= \frac{1}{11}x_1^{(k)} + \frac{1}{11}x_3^{(k-1)} - \frac{3}{11}x_4^{(k-1)} + \frac{25}{11} \\
 x_3^{(k)} &= -\frac{1}{5}x_1^{(k)} + \frac{1}{10}x_2^{(k)} + \frac{1}{10}x_4^{(k-1)} - \frac{11}{10} \\
 x_4^{(k)} &= -\frac{3}{8}x_2^{(k)} + \frac{1}{8}x_3^{(k)} + \frac{15}{8}
 \end{aligned}$$

The Gauss-Seidel Method

Solution (2/3)

When $\mathbf{x}^{(0)} = (0, 0, 0, 0)^t$, we have

$$\mathbf{x}^{(1)} = (0.6000, 2.3272, -0.9873, 0.8789)^t.$$

The Gauss-Seidel Method

Solution (2/3)

When $\mathbf{x}^{(0)} = (0, 0, 0, 0)^t$, we have

$\mathbf{x}^{(1)} = (0.6000, 2.3272, -0.9873, 0.8789)^t$. Subsequent iterations give the values in the following table:

k	0	1	2	3	4	5
$x_1^{(k)}$	0.0000	0.6000	1.030	1.0065	1.0009	1.0001
$x_2^{(k)}$	0.0000	2.3272	2.037	2.0036	2.0003	2.0000
$x_3^{(k)}$	0.0000	-0.9873	-1.014	-1.0025	-1.0003	-1.0000
$x_4^{(k)}$	0.0000	0.8789	0.984	0.9983	0.9999	1.0000

The Gauss-Seidel Method

Solution (3/3)

Because

$$\frac{\|\mathbf{x}^{(5)} - \mathbf{x}^{(4)}\|_{\infty}}{\|\mathbf{x}^{(5)}\|_{\infty}} = \frac{0.0008}{2.000} = 4 \times 10^{-4}$$

$\mathbf{x}^{(5)}$ is accepted as a reasonable approximation to the solution.

The Gauss-Seidel Method

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$$\frac{\|\mathbf{x}^{(5)} - \mathbf{x}^{(4)}\|_{\infty}}{\|\mathbf{x}^{(5)}\|_{\infty}} = \frac{0.0008}{2.000} = 4 \times 10^{-4}$$

$\mathbf{x}^{(5)}$ is accepted as a reasonable approximation to the solution.

Note that, in an earlier example, Jacobi's method required twice as many iterations for the same accuracy.

The Gauss-Seidel Method: Matrix Form

Re-Writing the Equations

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by a_{ii} and collect all k th iterate terms, to give

$$a_{i1} x_1^{(k)} + a_{i2} x_2^{(k)} + \dots + a_{ii} x_i^{(k)} = -a_{i,i+1} x_{i+1}^{(k-1)} - \dots - a_{in} x_n^{(k-1)} + b_i$$

for each $i = 1, 2, \dots, n$.

The Gauss-Seidel Method: Matrix Form

Re-Writing the Equations (Cont'd)

Writing all n equations gives

$$\begin{aligned}
 a_{11}x_1^{(k)} &= -a_{12}x_2^{(k-1)} - a_{13}x_3^{(k-1)} - \cdots - a_{1n}x_n^{(k-1)} + b_1 \\
 a_{21}x_1^{(k)} + a_{22}x_2^{(k)} &= -a_{23}x_3^{(k-1)} - \cdots - a_{2n}x_n^{(k-1)} + b_2 \\
 &\vdots \\
 a_{n1}x_1^{(k)} + a_{n2}x_2^{(k)} + \cdots + a_{nn}x_n^{(k)} &= b_n
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With the definitions of D , L , and U given previously, we have the Gauss-Seidel method represented by

$$(D - L)\mathbf{x}^{(k)} = U\mathbf{x}^{(k-1)} + \mathbf{b}$$

The Gauss-Seidel Method: Matrix Form

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Re-Writing the Equations (Cont'd)

Solving for $\mathbf{x}^{(k)}$ finally gives

$$\mathbf{x}^{(k)} = (D - L)^{-1}U\mathbf{x}^{(k-1)} + (D - L)^{-1}\mathbf{b}, \quad \text{for each } k = 1, 2, \dots$$

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Letting $T_g = (D - L)^{-1}U$ and $\mathbf{c}_g = (D - L)^{-1}\mathbf{b}$, gives the Gauss-Seidel technique the form

$$\mathbf{x}^{(k)} = T_g\mathbf{x}^{(k-1)} + \mathbf{c}_g$$

The Gauss-Seidel Method: Matrix Form

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$$\mathbf{x}^{(k)} = T_g\mathbf{x}^{(k-1)} + \mathbf{c}_g$$

For the lower-triangular matrix $D - L$ to be nonsingular, it is necessary and sufficient that $a_{ii} \neq 0$, for each $i = 1, 2, \dots, n$.

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Gauss-Seidel Iterative Algorithm (1/2)

To solve $A\mathbf{x} = \mathbf{b}$ given an initial approximation $\mathbf{x}^{(0)}$:

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INPUT the number of equations and unknowns n ;
 the entries a_{ij} , $1 \leq i, j \leq n$ of the matrix A ;
 the entries b_i , $1 \leq i \leq n$ of \mathbf{b} ;
 the entries x_{i0} , $1 \leq i \leq n$ of $\mathbf{x}^0 = \mathbf{x}^{(0)}$;
 tolerance TOL ;
 maximum number of iterations N .

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the entries b_i , $1 \leq i \leq n$ of \mathbf{b} ;
the entries $x_i^{(0)}$, $1 \leq i \leq n$ of $\mathbf{x}^{(0)}$;
tolerance TOL ;
maximum number of iterations N .

OUTPUT the approximate solution x_1, \dots, x_n or a message
that the number of iterations was exceeded.

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Step 7 OUTPUT ('Maximum number of iterations exceeded')
 STOP *(The procedure was unsuccessful)*

Gauss-Seidel Iterative Algorithm

Comments on the Algorithm

- Step 3 of the algorithm requires that $a_{ii} \neq 0$, for each $i = 1, 2, \dots, n$.

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- Another possible stopping criterion in Step 4 is to iterate until

$$\frac{\|\mathbf{x}^{(k)} - \mathbf{x}^{(k-1)}\|}{\|\mathbf{x}^{(k)}\|}$$

is smaller than some prescribed tolerance.

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- For this purpose, any convenient norm can be used, the usual being the l_∞ norm.

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Convergence Results for General Iteration Methods

Introduction

- To study the convergence of general iteration techniques, we need to analyze the formula

$$\mathbf{x}^{(k)} = T\mathbf{x}^{(k-1)} + \mathbf{c}, \quad \text{for each } k = 1, 2, \dots$$

where $\mathbf{x}^{(0)}$ is arbitrary.

- The following lemma and the earlier [Theorem](#) on convergent matrices provide the key for this study.

Convergence Results for General Iteration Methods

Lemma

If the spectral radius satisfies $\rho(T) < 1$, then $(I - T)^{-1}$ exists, and

$$(I - T)^{-1} = I + T + T^2 + \dots = \sum_{j=0}^{\infty} T^j$$

Convergence Results for General Iteration Methods

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Proof (1/2)

- Because $T\mathbf{x} = \lambda\mathbf{x}$ is true precisely when $(I - T)\mathbf{x} = (1 - \lambda)\mathbf{x}$, we have λ as an eigenvalue of T precisely when $1 - \lambda$ is an eigenvalue of $I - T$.

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- But $|\lambda| \leq \rho(T) < 1$, so $\lambda = 1$ is not an eigenvalue of T , and 0 cannot be an eigenvalue of $I - T$.
- Hence, $(I - T)^{-1}$ exists.

Convergence Results for General Iteration Methods

Proof (2/2)

Let

$$S_m = I + T + T^2 + \cdots + T^m$$

Convergence Results for General Iteration Methods

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Then

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and, since T is convergent, the [Theorem](#) on convergent matrices implies that

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Convergence Results for General Iteration Methods

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Thus, $(I - T)^{-1} = \lim_{m \rightarrow \infty} S_m = I + T + T^2 + \cdots = \sum_{j=0}^{\infty} T^j$

Convergence Results for General Iteration Methods

Theorem

For any $\mathbf{x}^{(0)} \in \mathbb{R}^n$, the sequence $\{\mathbf{x}^{(k)}\}_{k=0}^{\infty}$ defined by

$$\mathbf{x}^{(k)} = T\mathbf{x}^{(k-1)} + \mathbf{c}, \quad \text{for each } k \geq 1$$

converges to the unique solution of

$$\mathbf{x} = T\mathbf{x} + \mathbf{c}$$

if and only if $\rho(T) < 1$.

Convergence Results for General Iteration Methods

Proof (1/5)

First assume that $\rho(T) < 1$.

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First assume that $\rho(T) < 1$. Then,

$$\begin{aligned}\mathbf{x}^{(k)} &= T\mathbf{x}^{(k-1)} + \mathbf{c} \\ &= T(T\mathbf{x}^{(k-2)} + \mathbf{c}) + \mathbf{c}\end{aligned}$$

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Because $\rho(T) < 1$, the [Theorem](#) on convergent matrices implies that T is convergent, and

$$\lim_{k \rightarrow \infty} T^k \mathbf{x}^{(0)} = \mathbf{0}$$

Convergence Results for General Iteration Methods

Proof (2/5)

The previous lemma implies that

$$\lim_{k \rightarrow \infty} \mathbf{x}^{(k)} = \lim_{k \rightarrow \infty} T^k \mathbf{x}^{(0)} + \left(\sum_{j=0}^{\infty} T^j \right) \mathbf{c}$$

Convergence Results for General Iteration Methods

Proof (2/5)

The previous lemma implies that

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Convergence Results for General Iteration Methods

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Hence, the sequence $\{\mathbf{x}^{(k)}\}$ converges to the vector $\mathbf{x} \equiv (I - T)^{-1} \mathbf{c}$ and $\mathbf{x} = T\mathbf{x} + \mathbf{c}$.

Convergence Results for General Iteration Methods

Proof (3/5)

- To prove the converse, we will show that for any $\mathbf{z} \in \mathbb{R}^n$, we have $\lim_{k \rightarrow \infty} T^k \mathbf{z} = \mathbf{0}$.

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- Define $\mathbf{x}^{(0)} = \mathbf{x} - \mathbf{z}$, and, for $k \geq 1$, $\mathbf{x}^{(k)} = T\mathbf{x}^{(k-1)} + \mathbf{c}$.
- Then $\{\mathbf{x}^{(k)}\}$ converges to \mathbf{x} .

Convergence Results for General Iteration Methods

Proof (4/5)

Also,

$$\mathbf{x} - \mathbf{x}^{(k)} = (T\mathbf{x} + \mathbf{c}) - (T\mathbf{x}^{(k-1)} + \mathbf{c}) = T(\mathbf{x} - \mathbf{x}^{(k-1)})$$

Convergence Results for General Iteration Methods

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Convergence Results for General Iteration Methods

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- Hence

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- But $\mathbf{z} \in \mathbb{R}^n$ was arbitrary, so by the theorem on convergent matrices, T is convergent and $\rho(T) < 1$.

Convergence Results for General Iteration Methods

Corollary

$\|T\| < 1$ for any natural matrix norm and \mathbf{c} is a given vector, then the sequence $\{\mathbf{x}^{(k)}\}_{k=0}^{\infty}$ defined by

$$\mathbf{x}^{(k)} = T\mathbf{x}^{(k-1)} + \mathbf{c}$$

converges, for any $\mathbf{x}^{(0)} \in \mathbb{R}^n$, to a vector $\mathbf{x} \in \mathbb{R}^n$, with $\mathbf{x} = T\mathbf{x} + \mathbf{c}$, and the following error bounds hold:

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The proof of the following corollary is similar to that for the [Corollary](#) to the Fixed-Point Theorem for a single nonlinear equation.

Outline

- 1 The Gauss-Seidel Method
- 2 The Gauss-Seidel Algorithm
- 3 Convergence Results for General Iteration Methods
- 4 Application to the Jacobi & Gauss-Seidel Methods**

Convergence of the Jacobi & Gauss-Seidel Methods

Using the Matrix Formulations

We have seen that the Jacobi and Gauss-Seidel iterative techniques can be written

$$\mathbf{x}^{(k)} = T_j \mathbf{x}^{(k-1)} + \mathbf{c}_j \quad \text{and}$$

$$\mathbf{x}^{(k)} = T_g \mathbf{x}^{(k-1)} + \mathbf{c}_g$$

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using the matrices

$$T_j = D^{-1}(L + U) \quad \text{and} \quad T_g = (D - L)^{-1}U$$

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respectively. If $\rho(T_j)$ or $\rho(T_g)$ is less than 1, then the corresponding sequence $\{\mathbf{x}^{(k)}\}_{k=0}^{\infty}$ will converge to the solution \mathbf{x} of $A\mathbf{x} = \mathbf{b}$.

Convergence of the Jacobi & Gauss-Seidel Methods

Example

For example, the Jacobi method has

$$\mathbf{x}^{(k)} = D^{-1}(L + U)\mathbf{x}^{(k-1)} + D^{-1}\mathbf{b},$$

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This implies that

$$D\mathbf{x} = (L + U)\mathbf{x} + \mathbf{b} \quad \text{and} \quad (D - L - U)\mathbf{x} = \mathbf{b}$$

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Since $D - L - U = A$, the solution \mathbf{x} satisfies $A\mathbf{x} = \mathbf{b}$.

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Convergence of the Jacobi & Gauss-Seidel Methods

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Theorem

If A is strictly diagonally dominant, then for any choice of $\mathbf{x}^{(0)}$, both the Jacobi and Gauss-Seidel methods give sequences $\{\mathbf{x}^{(k)}\}_{k=0}^{\infty}$ that converge to the unique solution of $A\mathbf{x} = \mathbf{b}$.

Convergence of the Jacobi & Gauss-Seidel Methods

Is Gauss-Seidel better than Jacobi?

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- No general results exist to tell which of the two techniques, Jacobi or Gauss-Seidel, will be most successful for an arbitrary linear system.

Convergence of the Jacobi & Gauss-Seidel Methods

Is Gauss-Seidel better than Jacobi?

- No general results exist to tell which of the two techniques, Jacobi or Gauss-Seidel, will be most successful for an arbitrary linear system.
- In special cases, however, the answer is known, as is demonstrated in the following theorem.

Convergence of the Jacobi & Gauss-Seidel Methods

(Stein-Rosenberg) Theorem

If $a_{ij} \leq 0$, for each $i \neq j$ and $a_{ii} > 0$, for each $i = 1, 2, \dots, n$, then one and only one of the following statements holds:

- (i) $0 \leq \rho(T_g) < \rho(T_j) < 1$
- (ii) $1 < \rho(T_j) < \rho(T_g)$
- (iii) $\rho(T_j) = \rho(T_g) = 0$
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For the proof of this result, see pp. 120–127. of

Young, D. M., [Iterative solution of large linear systems](#), Academic Press, New York, 1971, 570 pp.

Convergence of the Jacobi & Gauss-Seidel Methods

Two Comments on the Theorem

- For the special case described in the theorem, we see from part (i), namely

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Convergence of the Jacobi & Gauss-Seidel Methods

Two Comments on the Theorem

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Convergence of the Jacobi & Gauss-Seidel Methods

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that when one method gives convergence, then both give convergence, and the Gauss-Seidel method converges **faster** than the Jacobi method.

Convergence of the Jacobi & Gauss-Seidel Methods

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that when one method gives convergence, then both give convergence, and the Gauss-Seidel method converges **faster** than the Jacobi method.

- Part (ii), namely

$$1 < \rho(T_j) < \rho(T_g)$$

indicates that when one method diverges then both diverge, and the **divergence is more pronounced** for the Gauss-Seidel method.

Questions?

Eigenvalues & Eigenvectors: Convergent Matrices

Theorem

The following statements are equivalent.

- (i) A is a convergent matrix.
- (ii) $\lim_{n \rightarrow \infty} \|A^n\| = 0$, for some natural norm.
- (iii) $\lim_{n \rightarrow \infty} \|A^n\| = 0$, for all natural norms.
- (iv) $\rho(A) < 1$.
- (v) $\lim_{n \rightarrow \infty} A^n \mathbf{x} = \mathbf{0}$, for every \mathbf{x} .

The proof of this theorem can be found on p. 14 of Issacson, E. and H. B. Keller, [Analysis of Numerical Methods](#), John Wiley & Sons, New York, 1966, 541 pp.

[Return to General Iteration Methods — Introduction](#)

[Return to General Iteration Methods — Lemma](#)

[Return to General Iteration Methods — Theorem](#)

Fixed-Point Theorem

Let $g \in C[a, b]$ be such that $g(x) \in [a, b]$, for all x in $[a, b]$. Suppose, in addition, that g' exists on (a, b) and that a constant $0 < k < 1$ exists with

$$|g'(x)| \leq k, \quad \text{for all } x \in (a, b).$$

Then for any number p_0 in $[a, b]$, the sequence defined by

$$p_n = g(p_{n-1}), \quad n \geq 1$$

converges to the unique fixed point p in $[a, b]$.

[Return to the Corollary to the Fixed-Point Theorem](#)

Corollary to the Fixed-Point Convergence Result

If g satisfies the hypothesis of the Fixed-Point [Theorem](#) then

$$|p_n - p| \leq \frac{k^n}{1 - k} |p_1 - p_0|$$

[Return to the Corollary to the Convergence Theorem for General Iterative Methods](#)