

# Math 541 - Numerical Analysis

## Lecture Notes – Zeros and Roots

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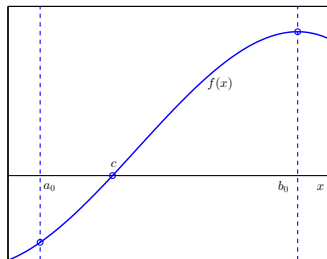
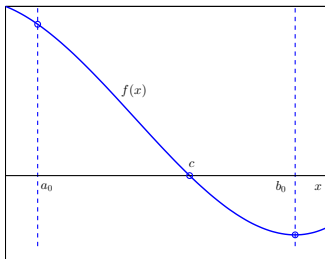
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# Outline

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# Intermediate Value Theorem

- Suppose  $f$  is continuous on the interval  $(a_0, b_0)$  and  $f(a_0) \cdot f(b_0) < 0$ 
  - This means the function changes sign at least once in the interval
- The **Intermediate Value Theorem** guarantees the existence of  $c \in (a_0, b_0)$  such that  $f(c) = 0$  (could be more than one)



## The Bisection Method

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The **Bisection Method** approximates the root ( $f(c) = 0$ ) of a **continuous function** that changes sign at least once for  $x \in [a_0, b_0]$

- Thus,  $f(a_0) \cdot f(b_0) < 0$
- Iteratively find the **midpoint**

$$m_k = \frac{a_k + b_k}{2}$$

- If  $f(m_k) = 0$ , we're done
- Check if  $f(m_k) \cdot f(b_k) < 0$  or  $f(m_k) \cdot f(a_k) < 0$
- If  $f(m_k) \cdot f(b_k) < 0$ , then  $c \in [m_k, b_k]$  and we take  $a_{k+1} = m_k$  and  $b_{k+1} = b_k$
- Otherwise  $f(m_k) \cdot f(a_k) < 0$ , and  $c \in [a_k, m_k]$ , so we take  $b_{k+1} = m_k$  and  $a_{k+1} = a_k$

## The Bisection Method

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The **Bisection Method** for solving  $f(c) = 0$  from the previous slide:

- Constructs a sequence of intervals containing the root  $c$ :

$$(a_0, b_0) \supset (a_1, b_1) \supset \cdots \supset (a_{n-1}, b_{n-1}) \supset (a_n, b_n) \ni c$$

- After  $k$  steps

$$|b_k - a_k| = \frac{1}{2} |b_{k-1} - a_{k-1}| = \left(\frac{1}{2}\right)^k |b_0 - a_0|$$

- At step  $k$ , the midpoint  $m_k = \frac{a_k + b_k}{2}$  is an estimate for the root  $c$  with

$$m_k - d_k \leq c \leq m_k + d_k, \quad d_k = \left(\frac{1}{2}\right)^{k+1} |b_0 - a_0|$$

## The Bisection Method

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**Convergence** is slow:

- At each step we gain *one binary digit in accuracy*
- Since  $10^{-1} \approx 2^{-3.3}$ , it takes on average 3.3 iterations to gain one decimal digit of accuracy
- **Note:** The rate of convergence is completely independent of the function  $f$
- We are only using the **sign of  $f$**  at the endpoints of the interval(s) to make decisions on how to update
- By making more effective use of the values of  $f$  we can attain significantly faster convergence

## Example: Bisection Method

1 of 5

The bisection method applied to

$$f(x) = \left(\frac{x}{2}\right)^2 - \sin(x) = 0$$

with  $(a_0, b_0) = (1.5, 2.0)$ , and  $(f(a_0), f(b_0)) = (-0.4350, 0.0907)$  gives:

$k$	$a_k$	$b_k$	$m_k$	$f(m_k)$
0	1.5000	2.0000	1.7500	-0.2184
1	1.7500	2.0000	1.8750	-0.0752
2	1.8750	2.0000	1.9375	0.0050
3	1.8750	1.9375	1.9062	-0.0358
4	1.9062	1.9375	1.9219	-0.0156
5	1.9219	1.9375	1.9297	-0.0054
6	1.9297	1.9375	1.9336	-0.0002
7	1.9336	1.9375	1.9355	0.0024
8	1.9336	1.9355	1.9346	0.0011
9	1.9336	1.9346	1.9341	0.0004

## Example: Bisection Method

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This **MatLab code** can easily be modified to any *function*

```
1 function root = bisection(a,b,tol)
2 %BISECTION METHOD - Modify function below, then can
3 % find its roots in [a,b] to tolerance tol
4 f = @(x) (x/2).^2 - sin(x);
5 while (abs(b-a) >= tol)
6     m = (a+b)/2;
7     if (f(m) == 0)
8         break;
9     elseif (f(b)*f(m) < 0)
10        a = m;
11    else
12        b = m;
13    end
14 end
15 root = m;
```

Demonstrate in class



## Example: Bisection Method

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This **MatLab code** (2 Slides) graphically shows example

```
1 % WARNING: This example ASSUMES that f(a)<0<f(b)...
2 x = 1.5:0.001:2;
3 f = inline('(x/2).^2-sin(x)', 'x');
4 a = 1.5;
5 b = 2.0;
6 for k = 0:9
7 plot(x, f(x), 'k-', 'linewidth', 2)
8 axis([1.45 2.05 -0.5 .15])
9 grid on
10 hold on
11 plot([a b], f([a b]), 'ko', 'linewidth', 5)
12 plot([1.45 2.05], [0 0], 'r:')
13 hold off
```

## Example: Bisection Method

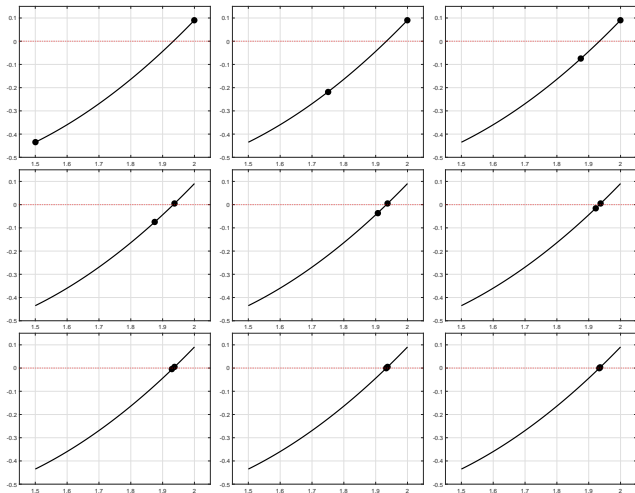
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```
14 m = (a+b)/2;
15 if( f(m) < 0 )
16 a = m;
17 else
18 b = m;
19 end
20 pause
21 print('-depsec', ['bisecc' int2str(k) '.eps'], '-f1');
22 end
```

The next Slides show the **output**

# Example: Bisection Method

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## Stopping Criteria

When do we stop?

We can (1) keep going until successive iterates are close:

$$|m_k - m_{k-1}| < \epsilon$$

or (2) close in relative terms

$$\frac{|m_k - m_{k-1}|}{|m_k|} < \epsilon$$

or (3) the function value is small enough

$$|f(m_k)| < \epsilon$$

No choice is perfect. In general, where no additional information about  $f$  is known, the second criterion is the preferred one (since it comes the closest to testing the relative error).

# Rate of Convergence

Suppose an **algorithm** generates a **sequence** of **approximations**,  $c_n$ , which approaches a limit,  $c_*$ , or

$$\lim_{n \rightarrow \infty} c_n = c_*$$

How quickly does  $c_n \rightarrow c_*$ ?

## Definition (Rate of Convergence)

If a sequence  $c_1, c_2, \dots, c_n$  converges to a value  $c_*$  and if there exist real numbers  $\lambda > 0$  and  $\alpha \geq 1$  such that

$$\lim_{n \rightarrow \infty} \frac{|c_{n+1} - c_*|}{|c_n - c_*|^\alpha} = \lambda$$

then we say that  $\alpha$  is the **rate of convergence** of the sequence.

# Cauchy Sequence

## Definition (Cauchy Sequence)

Consider a sequence  $c_1, c_2, \dots, c_n$  of real numbers. This sequence is called a **Cauchy sequence**, if for every  $\varepsilon > 0$ , there is a positive integer  $N$  such that for all natural numbers  $m, n > N$ ,

$$|x_m - x_n| < \varepsilon.$$

From the properties of real numbers (**completeness**), a **Cauchy sequence**,  $\{c_n\}$  converges to a unique real number  $c_*$ .

# Rate of Convergence - Cauchy

A **Numerical algorithm** produces a sequence of **approximations**,  $\{c_n\}$ , which is hopefully converging to a limit,  $c_*$ , which is **NOT** known.

How can the sequence  $\{c_n\}$  be used to find the *rate of convergence*?

## Definition (Rate of Cauchy Convergence)

If a sequence  $c_1, c_2, \dots, c_n$  converges and if there exist real numbers  $\lambda > 0$  and  $\alpha \geq 1$  such that

$$\lim_{n \rightarrow \infty} \frac{|c_{n+1} - c_n|}{|c_n - c_{n-1}|^\alpha} = \lambda$$

then we say that  $\alpha$  is the *rate of convergence* of the sequence.

# Numerical Rate of Convergence

Suppose a **Numerical algorithm** produces a sequence of **approximations**,  $\{c_n\}$ .

The *rate of Cauchy convergence*,  $\alpha$ , for the sequence  $c_1, c_2, \dots, c_n$  is derived from the existence of real numbers  $\lambda > 0$  and  $\alpha \geq 1$  with

$$\lim_{n \rightarrow \infty} \frac{|c_{n+1} - c_n|}{|c_n - c_{n-1}|^\alpha} = \lambda.$$

By taking logarithms of the expression above, we have

$$\ln |c_{n+1} - c_n| = \alpha \ln |c_n - c_{n-1}| + \ln(\lambda).$$

Let  $Y_n = \ln |c_{n+1} - c_n|$  and  $X_n = \ln |c_n - c_{n-1}|$ , which are readily computed from the sequence, then the *rate of Cauchy convergence*,  $\alpha$ , is approximated by the *slope* of the best fitting line through  $(X_n, Y_n)$ .



# Rate of Convergence - Bisection Method

Let  $c_*$  be a **root** of  $f$ , so  $f(c_*) = 0$

Let  $m_n = \frac{a_n + b_n}{2}$  be the **midpoint** between the endpoints of the interval  $[a_n, b_n]$ , which comes from  $n$  iterations of the **Bisection Method** and where  $c_* \in [a_n, b_n]$

Earlier we showed that at most

$$|m_n - c_*| \leq \frac{1}{2^{n+1}} |b_0 - a_0|$$

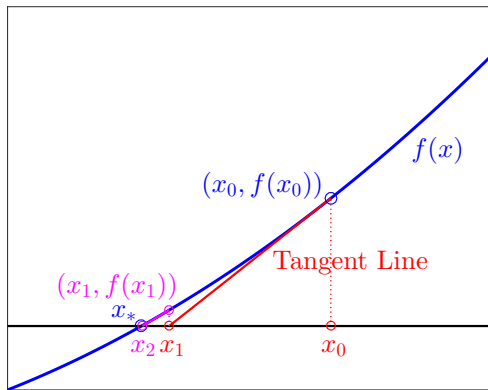
Form the **sequence of midpoints** with  $c_n = m_n$ , then from the worst case scenario

$$|c_n - c_*| \leq \frac{1}{2^{n+1}} |b_0 - a_0| \quad \text{or} \quad \frac{|c_{n+1} - c_*|}{|c_n - c_*|} \approx \frac{1}{2}$$

It follows that for **Bisection Method**  $\alpha = 1$ , so the **rate of convergence** is **linear**

# Tangent Lines

Start at  $x_0$ , then follow *tangent lines* of  $f(x)$  to their zeroes.  
 Iterate these zeroes **converging** to  $\{x_n\}_{n=0}^{\infty} \rightarrow x_*$  with  $f(x_*) = 0$ .



## Tangent Lines

- The graphic from previous slide seems to show rapid convergence to the zero of  $f(x)$
- The graph shows the use of properties of  $f(x)$
- Does this sequence always converge to  $x_*$ ?
- Assuming convergence, how rapidly does this sequence converge?
- The Method employs techniques from **Calculus**
- Technique is called **Newton's Method**
- What are properties of Newton's Method?

## Newton's Method for Root Finding

1 of 2

**Recall:** we are looking for  $x^*$  so that  $f(x^*) = 0$ .

If  $f \in C^2[a, b]$ , and we know  $x^* \in [a, b]$  (possibly by the intermediate value theorem), then we can formally Taylor expand around a point  $x$  close to the root:

$$0 = f(x^*) = f(x) + (x^* - x)f'(x) + \frac{(x - x^*)^2}{2} f''(\xi(x)), \quad \xi(x) \in [x, x^*].$$

If we are close to the root, then  $|x - x^*|$  is small, which means that  $|x - x^*|^2 \ll |x - x^*|$ , hence we make the approximation:

$$0 \approx f(x) + (x^* - x)f'(x), \quad \Leftrightarrow \quad x^* \approx x - \frac{f(x)}{f'(x)}.$$

## Newton's Method for Root Finding

2 of 2

**Newton's Method** for root finding is based on the approximation

$$x^* \approx x - \frac{f(x)}{f'(x)}$$

which is valid when  $x$  is close to  $x^*$ .

**Newton's Method**

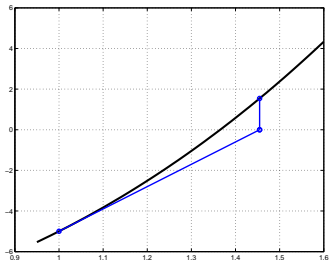
**Newton's Method** is an **iterative scheme**, where given an  $x_{n-1}$ , we compute

$$x_n = x_{n-1} - \frac{f(x_{n-1})}{f'(x_{n-1})}$$

If  $x_0$  is “sufficiently close” to a **root**,  $x^*$ , of  $f(x)$ , then iterations  $x_n$  give **improved approximations** of  $x^*$ , as  $n \rightarrow \infty$

**Geometrically**,  $x_n$  is the intersection of the tangent of the function at  $x_{n-1}$  and the  $x$ -axis.

## Two Steps of Newton for $f(x) = x^3 + 4x^2 - 10 = 0$



Start with  $p_0 = 1$

$$p_1 = p_0 - \frac{p_0^3 + 4p_0^2 - 10}{3p_0^2 + 8p_0} = 1.45454545454545$$

$$p_2 = p_1 - \frac{p_1^3 + 4p_1^2 - 10}{3p_1^2 + 8p_1} = 1.36890040106952$$

$$p^* = 1.365230013$$

From MAPLE

## MatLab Newton Code

```
1 function p = newton(p0,tol,Nmax)
2 %NEWTON'S METHOD: Enter f(x), f'(x), x0, tol, Nmax
3 f = @(x) x^3 + 4*x^2 - 10;
4 fp = @(x) 3*x^2 + 8*x;
5 p = p0 - f(p0)/fp(p0);
6 i = 1;
7 while (abs(p - p0) >= tol)
8     p0 = p;
9     p = p0 - f(p0)/fp(p0);
10    i = i + 1;
11    if (i >= Nmax)
12        fprintf('Fail after %d iterations\n',Nmax);
13        break
14    end
15 end
16 end
```

## Finding a Starting Point for Newton's Method

Recall our initial argument that when  $|x - x^*|$  is small, then  $|x - x^*|^2 \ll |x - x^*|$ , and we can neglect the second order term in the Taylor expansion.

In order for Newton's method to converge we need a *good starting point!*

### Theorem

*Let  $f(x) \in C^2[a, b]$ . If  $x^* \in [a, b]$  such that  $f(x^*) = 0$  and  $f'(x^*) \neq 0$ , then there exists a  $\delta > 0$  such that Newton's method generates a sequence  $\{x_n\}_{n=1}^{\infty}$  converging to  $x^*$  for any initial approximation  $x_0 \in [x^* - \delta, x^* + \delta]$ .*

The theorem is interesting, but quite useless for practical purposes. In practice: Pick a starting value  $x_0$ , iterate a few steps. Either the iterates converge quickly to the root, or it will be clear that convergence is unlikely.



## Newton's Method – Rate of Convergence

1 of 3

Suppose  $x^*$  is a root of  $f(x)$  and consider the Taylor expansion of  $f(x^*)$  about  $x_n$

$$0 = f(x^*) = f(x_n) + f'(x_n)(x^* - x_n) + \frac{f''(\xi_n)}{2}(x^* - x_n)^2,$$

where  $\xi_n \in (x^*, x_n)$

Dividing by  $f'(x_n)$  gives

$$\frac{f(x_n)}{f'(x_n)} + (x^* - x_n) = -\frac{f''(\xi_n)}{2f'(x_n)}(x^* - x_n)^2$$

but  $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$ , so

$$(x^* - x_{n+1}) = -\frac{f''(\xi_n)}{2f'(x_n)}(x^* - x_n)^2$$

## Newton's Method – Rate of Convergence

2 of 3

Taking absolute values

$$\frac{|x^* - x_{n+1}|}{|x^* - x_n|^2} = \frac{|f''(\xi_n)|}{2|f'(x_n)|},$$

so by our definition for *rate of convergence*, **Newton's Method** has *quadratic convergence* provided

- 1  $f'(x) \neq 0$ , for all  $x \in I$ , where  $I = [x^* - r, x^* + r]$  for some  $r \geq |x^* - x_0|$
- 2  $f''(x)$  is continuous for all  $x \in I$
- 3  $x_0$  is “sufficiently close” to  $x^*$

## Newton's Method – Rate of Convergence

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“Sufficiently close” means

- We can ignore higher order terms of the Taylor expansion
- $\frac{|f''(x_n)|}{2|f'(x_n)|} < C \frac{|f''(x^*)|}{|f'(x^*)|}$  for some  $C < \infty$
- $C \frac{|f''(x^*)|}{|f'(x^*)|} |x^* - x_n| < 1$  for all  $n$

If

$$M = \sup_{x \in I} \frac{|f''(x)|}{2|f'(x)|},$$

we have convergence for an initial point  $x_0$  provided  $M|x^* - x_0| < 1$

## MatLab Newton Example

1

```
1 function z = newtoneger(p0,tol,Nmax)
2 %NEWTON'S METHOD: Enter f(x), f'(x), x0, tol, Nmax
3 f = @(x) x^3 + 4*x^2 - 10;
4 fp = @(x) 3*x^2 + 8*x;
5 p = p0 - f(p0)/fp(p0);
6 z = [p]; i = 1;
7 while (abs(p - p0) ≥ tol)
8     p0 = p;
9     p = p0 - f(p0)/fp(p0);
10    z = [z,p];
11    i = i + 1;
12    if (i ≥ Nmax)
13        fprintf('Fail after %d iterations\n',Nmax);
14        break
15    end
16 end
17 end
```

## MatLab Newton Example

The previous code generates Newton iterates to solve

$$f(x) = x^3 + 4x^2 - 10 = 0$$

with the first **five** iterates being:

$$z = [1.454545454545455, \quad 1.368900401069519, \quad 1.365236600202116, \\ 1.365230013435367, \quad 1.365230013414097]$$

*Quadratic convergence* suggests examining:

$$Q_n = \frac{|z_{n+1} - z_n|}{|z_n - z_{n-1}|^2}.$$

Substituting the sequence  $\{z_n\}$  into the fraction above gives:

$$Q_2 = 0.49949, \quad Q_3 = 0.49069, \quad Q_4 = 0.49025.$$

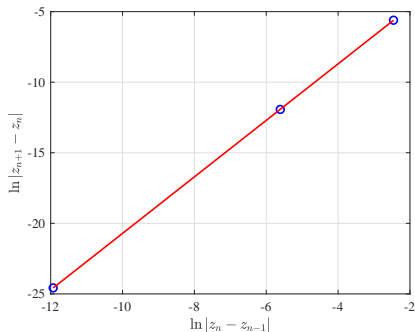
## MatLab Newton Example

3

```
1 xlab = '$\ln|z_{n}-z_{n-1}|$';           % X-label
2 ylab = '$\ln|z_{n+1}-z_{n}|$';         % Y-label
3 mytitle = '';                          % Title
4 z = newtoneger(1,1e-7,20);
5 %z = secanteger(1,2,1e-9,20);
6 N = length(z);
7 xx = log(abs(z(2:N-1)-z(1:N-2)));
8 yy = log(abs(z(3:N)-z(2:N-1)));
9 p = polyfit(xx,yy,1)
10 x1 = min(xx); x2 = max(xx);
11 y1 = p(1)*x1 + p(2);
12 y2 = p(1)*x2 + p(2);
13 plot(xx,yy,'bo','MarkerSize',7);
14 hold on
15 plot([x1,x2],[y1,y2],'r-','LineWidth',1.5);
16 grid
```

## MatLab Newton Example

The previous program plots  $Y_n = \ln |z_{n+1} - z_n|$  vs.  $X_n = \ln |z_n - z_{n-1}|$  and finds the slope, which is the *rate of convergence*.



The program gives the best fitting line:

$$Y_n = 2.0017 X_n - 0.69493.$$

## Summary: Newton's Method

**Newton's Method** solves  $f(x) = 0$  very efficiently

- Converges *quadratically* to the solution
- Roughly doubles the digits with each iteration when close
- Simple algorithm: Zero crossing of tangent line

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

### Problems:

- Difficult to determine the range of initial conditions for which Newton's method converges
- Algorithm often fails to converge
- Problems if  $f'(x) = 0$
- Computing the derivative can be “expensive”
- If the zero of  $f(x)$  isn't simple, then convergence is *linear*



# Secant Method

Main weakness of **Newton's Method** is computing the derivative

- Computing the derivative can be difficult
- Derivative often needs many more arithmetic operations

One solution is to **Approximate the Derivative**

By definition,

$$f'(x_{n-1}) = \lim_{x \rightarrow x_{n-1}} \frac{f(x) - f(x_{n-1})}{x - x_{n-1}}$$

Take  $x = x_{n-2}$ , then an approximation is

$$f'(x_{n-1}) \approx \frac{f(x_{n-2}) - f(x_{n-1})}{x_{n-2} - x_{n-1}}$$

# Secant Method

The approximation

$$f'(x_{n-1}) \approx \frac{f(x_{n-2}) - f(x_{n-1})}{x_{n-2} - x_{n-1}}$$

is inserted into Newton's method to give

## Secant Method

The **Secant Method** is an **iterative scheme**, where given an  $x_{n-2}$  and  $x_{n-1}$ , we compute

$$x_n = x_{n-1} - \frac{f(x_{n-1})(x_{n-2} - x_{n-1})}{f(x_{n-2}) - f(x_{n-1})}$$

## MatLab Secant Code

```
1 function xn = secant(x0,x1,tol,Nmax)
2 %SECANT METHOD: Enter f(x), x0, x1, tol, Nmax
3 f = @(x) x^3 + 4*x^2 - 10;
4 xn = x1 - f(x1)*(x1-x0)/(f(x1)-f(x0));
5 i = 1;
6 while (abs(xn - x1) >= tol)
7     x0 = x1;
8     x1 = xn;
9     xn = x1 - f(x1)*(x1-x0)/(f(x1)-f(x0));
10    i = i + 1;
11    if (i >= Nmax)
12        fprintf('Fail after %d iterations\n',Nmax);
13        break
14    end
15 end
16 end
```

# Secant Method – Convergence

The **Secant method** satisfies:

$$f'(x_{n-1}) \approx \frac{f(x_{n-2}) - f(x_{n-1})}{x_{n-2} - x_{n-1}}$$

- **Algorithm** requires two initial starting points
- New iterate is the zero crossing of the *secant line*
- Do **NOT** need a derivative, only **function** evaluations
- **Order of Convergence** is *superlinear*
  - Order of Convergence has been shown to be the *golden ratio*,  $\phi = \frac{1+\sqrt{5}}{2} \approx 1.6$
  - Faster than **Bisection method**, but slower than **Newton's method**

## MatLab Secant Example

1

```
1 function z = secanteger(x0,x1,tol,Nmax)
2 %SECANT METHOD: Enter f(x), x0, x1, tol, Nmax
3 f = @(x) x^3 + 4*x^2 - 10;
4 xn = x1 - f(x1)*(x1-x0)/(f(x1)-f(x0));
5 z=[xn]; i = 1;
6 while (abs(xn - x1) ≥ tol)
7     x0 = x1;
8     x1 = xn;
9     xn = x1 - f(x1)*(x1-x0)/(f(x1)-f(x0));
10    z=[z,xn];
11    i = i + 1;
12    if (i ≥ Nmax)
13        fprintf('Fail after %d iterations\n',Nmax);
14        break
15    end
16 end
17 end
```

## MatLab Secant Example

2

The previous code generates Secant iterates to solve

$$f(x) = x^3 + 4x^2 - 10 = 0$$

with the first **seven** iterates being:

$$z = [1.263157894736842, \quad 1.338827838827839, \quad 1.366616394719345, \\ 1.365211902631857, \quad 1.365230001110859, \quad 1.365230013414206 \\ 1.365230013414097]$$

*Superlinear convergence* with  $\alpha = \frac{1+\sqrt{5}}{2}$  suggests examining:

$$S_n = \frac{|z_{n+1} - z_n|}{|z_n - z_{n-1}|^\alpha}.$$

Substituting the sequence  $\{z_n\}$  into the fraction above gives:

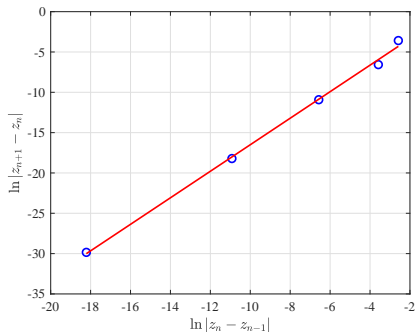
$$S_2 = 1.8105, \quad S_3 = 0.4628, \quad S_4 = 0.7465, \quad S_5 = 0.5799, \quad S_6 = 0.6871,$$

which is roughly constant.

## MatLab Secant Example

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The program with the Secant method on Slide 30 plots  $Y_n = \ln |z_{n+1} - z_n|$  vs.  $X_n = \ln |z_n - z_{n-1}|$  and finds the slope, which is the *rate of convergence*.



The program gives the best fitting line:

$$Y_n = 1.6444 X_n - 0.057042.$$

# Root Finding Methods

## The **Bisection method**

- **Very stable Algorithm** - Good technique to find starting point for Newton's method
- Costs only one function evaluation, so rapid iterations
- *Linear* convergence, so slow (3.3 iterations/digit)

## The **Secant method**

- Hard to find starting points (Unknown **basin of attraction**)
- Costs only two function evaluations, so rapid iterations
- *Superlinear* convergence,  $\alpha \approx 1.62$ , which is pretty fast

## The **Newton's method**

- Hard to find starting points (Unknown **basin of attraction**)
- Finding and evaluating derivative requires more machine work at each iteration
- *Quadratic* convergence is very fast – doubling the digits at each iteration



## Example

Return to Example:

$$f(x) = x^3 + 4x^2 - 10$$

We know the root is between  $x = 1$  and  $x = 1.5$ . (Use for **Bisection** and **Secant** methods)

$n$	Bisection	Secant	Newton
1	1.25	1.33898305084745	1.45454545454545
2	1.375	1.36356284991687	1.36890040106951
3	1.3125	1.36525168742565	1.36523660020211
4	1.34375	1.36522999568865	1.36523001343536
5	1.359375	1.36523001341391	1.36523001341409
6	1.3671875	1.36523001341409	
7	1.36328125		
8	1.365234375		
9	1.3642578125		
10	1.36474609375		
11	1.364990234375		
12	1.3651123046875		

# Modifying Newton's Method

The local nature of **Newton's method** means that we are stuck with problems of finding the *basin of attraction* for the root,  $p^*$ , where  $f(p^*) = 0$

The **Bisection method** is a stable routine often used to narrow the search of  $p_0$ , so that **Newton's method** converges

Another major problem is that **Newton's method** breaks when  $f'(p^*) = 0$  (division by zero).

The good news is that this problem can be fixed!

— We need a short discussion on the *multiplicity of zeroes*.

## Multiplicity of Zeroes

1 of 2

## Definition (Multiplicity of a Root)

A solution  $p^*$  of  $f(x) = 0$  is a **zero of multiplicity**  $m$  of  $f$  if for  $x \neq p^*$  we can write

$$f(x) = (x - p^*)^m q(x), \quad \lim_{x \rightarrow p^*} q(x) \neq 0$$

Basically,  $q(x)$  is the part of  $f(x)$  which does not contribute to the zero of  $f(x)$

If  $m = 1$  then we say that  $f(x)$  has a *simple zero*.

## Theorem

$f \in C^1[a, b]$  has a simple zero at  $p^*$  in  $(a, b)$  if and only if  $f(p^*) = 0$ , but  $f'(p^*) \neq 0$ .

## Multiplicity of Zeroes

2 of 2

## Theorem (Multiplicity and Derivatives)

The function  $f \in C^m[a, b]$  has a zero of multiplicity  $m$  at  $p^*$  in  $(a, b)$  if and only if

$$0 = f(p^*) = f'(p^*) = \dots = f^{(m-1)}(p^*), \quad \text{but } f^{(m)}(p^*) \neq 0.$$

We know that Newton's method runs into trouble when we have a zero of multiplicity higher than 1

**Newton's method** only converges *linearly* in these cases

**Halley's method** is a modification that converges *cubically*, in general, and *quadratically* for higher order roots

# Halley's Method for Zeroes of Higher Multiplicity

Halley's Method (for Zeroes of Multiplicity  $\geq 2$ )

$$x_{n+1} = x_n - \frac{f(x_n)f'(x_n)}{[f'(x_n)]^2 - f(x_n)f''(x_n)}$$

## Drawbacks:

We have to compute  $f''(x)$  — more expensive and possibly another source of numerical and/or measurement errors.

We have to compute a more complicated expression in each iteration — more expensive.

Roundoff errors in the denominator — both  $f'(x)$  and  $f(x)$  approach zero, so we are computing the difference between two small numbers; a serious cancellation risk.